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Geodesy on the move

Dealing with dynamic coordinate reference systems

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IOGP Geomatics Industry Day

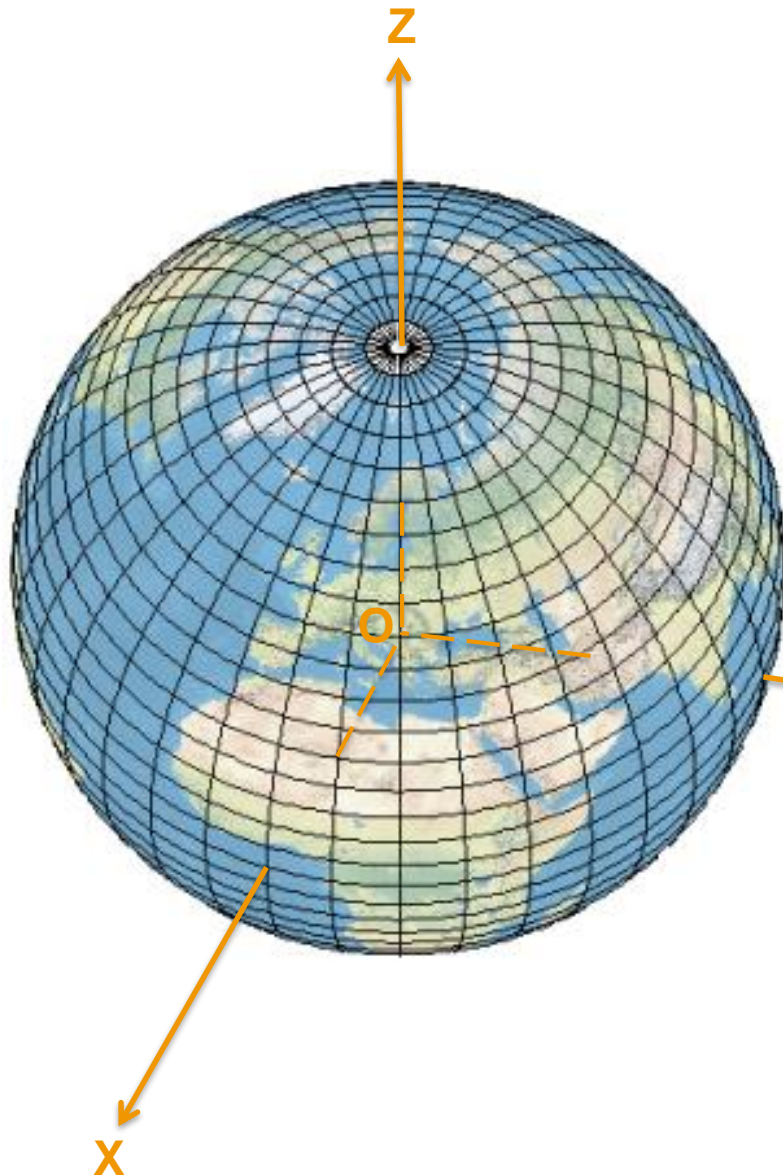
Stavanger, April 2017

Historic geodesy

- datum origin and geodetic network on the Earth's crust
- CRS is national or regional
- examples: ED50, NAD27, NAD83(86), AGD66, AGD84
- coordinates do not change with time = “static”.
- mental image of a solid Earth: “Third Rock from the Sun”



Earth-centred, earth-fixed frame



- geocentric Cartesian reference frame co-rotates with the Earth as a whole.

- CRS is global

- examples:
ITRS ITRF88...ITRF2014
IGSxx IGS00...IGb08

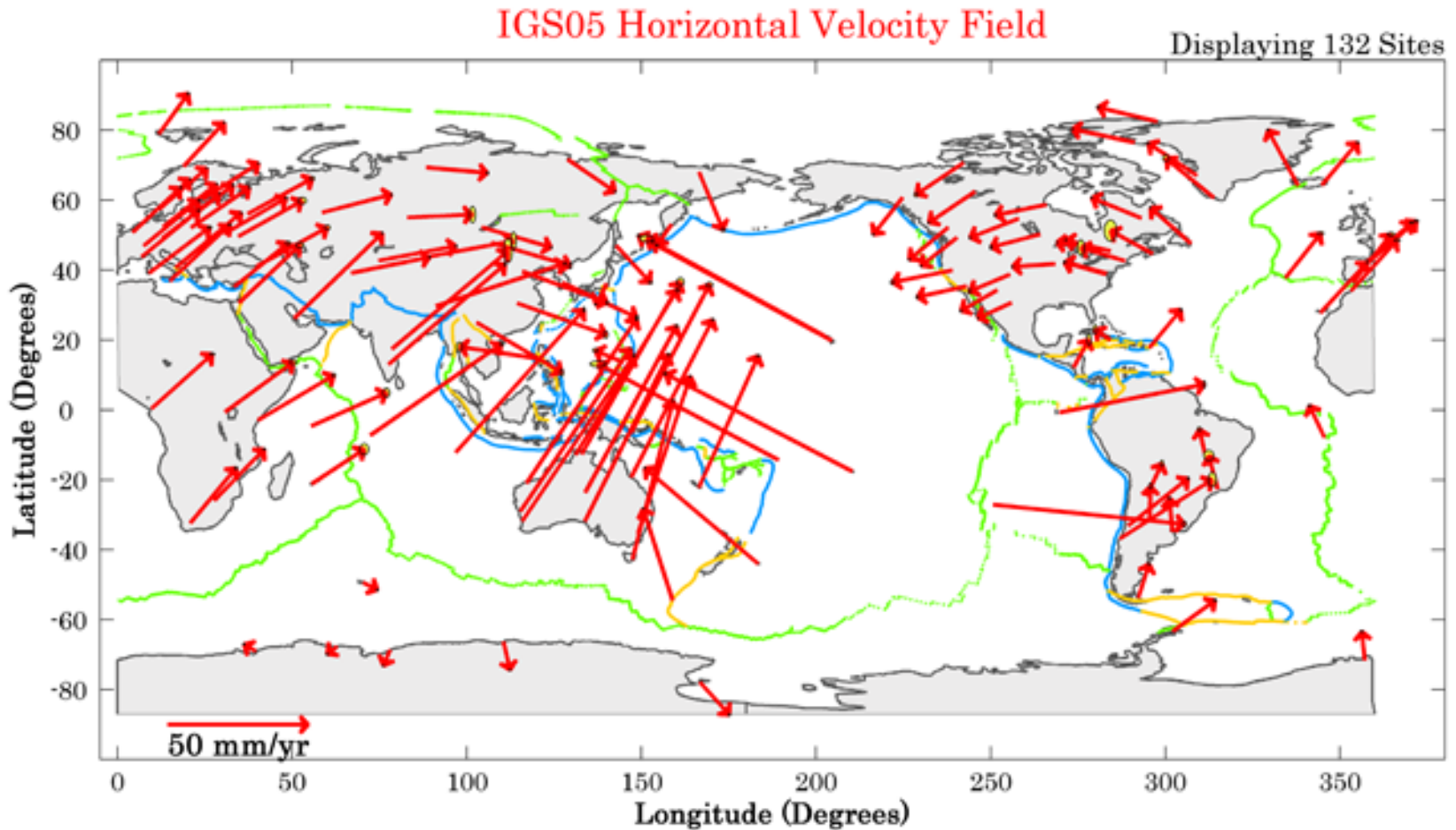
GNSS CRSs:

WGS 84 ...WGS 84(G1762)

PZ-90 ...PZ-90.11

etc.

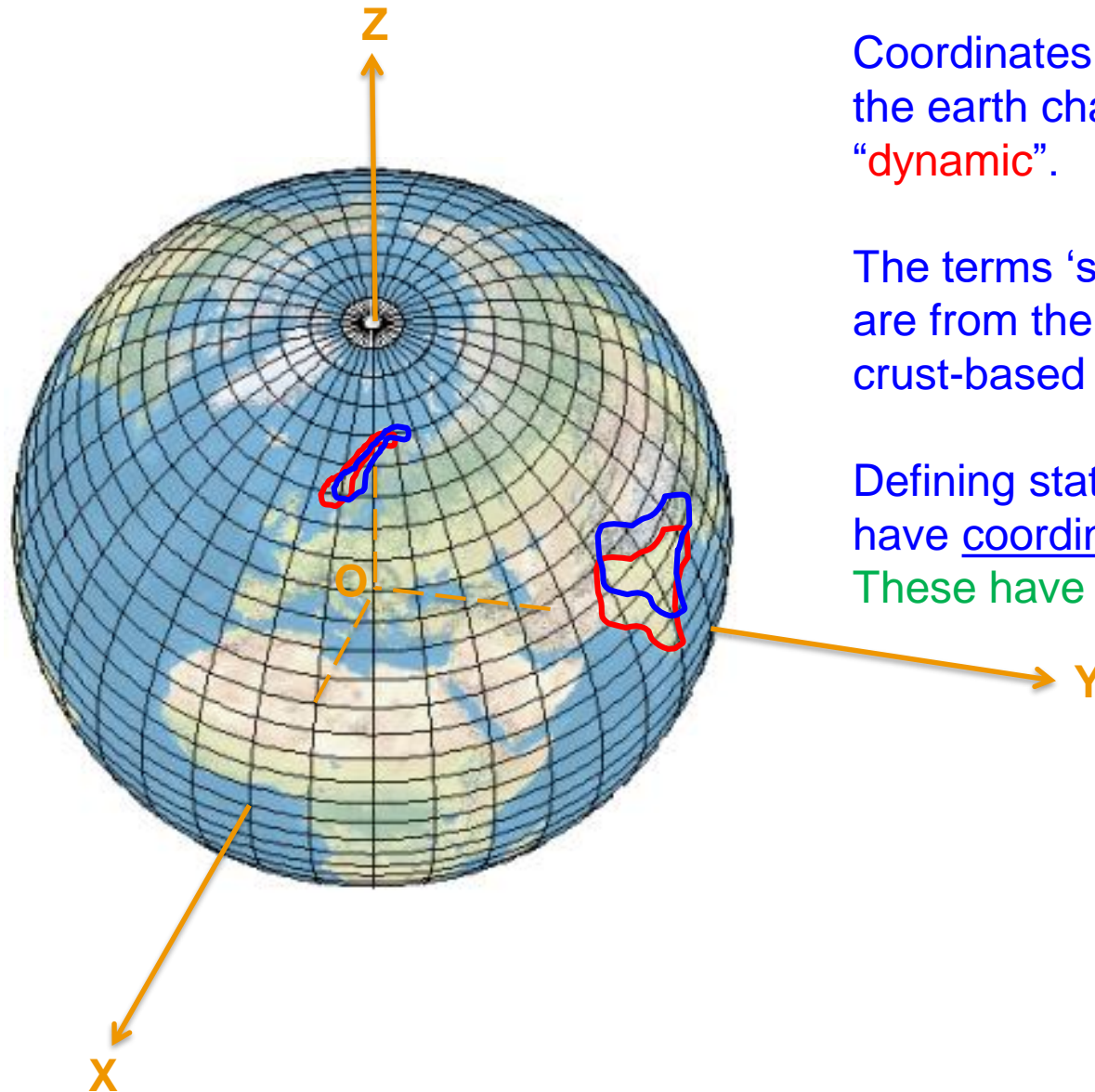
Tectonic plate velocities



EU \approx 2.5 cm/yr

Australia \approx 7 cm/yr

Plate motion in an ECEF frame



Coordinates on the surface of the earth change with time: “dynamic”.

The terms ‘static’ and ‘dynamic’ are from the viewpoint of a crust-based observer.

Defining stations (on crust) have coordinates and rates. These have a reference epoch.

ITRF-based static CRSs

- Snapshot of global dynamic system
 - defined to be same as ITRFxx at a specific reference epoch ...
 - ... but fixed to a plate – regional – **static**
- examples:
 - ETRF89, NAD83(2011), GDA94, GDA2020
 - modern national geodesy
- reference from ITRF dealt with by time-dependent transformation
 - when ITRF updated, may be a new transformation and realization
 - ETRF89 ... ETRF2000
 - NAD83(CSRS)v2 ... NAD83(CSRS)v7

Semi-dynamic reference frames

Hybrid, hoping to get best of all worlds

- **static** for applications that can ignore tectonic motion
- **dynamic** for those that require highest accuracy
- national or regional

Two approaches:

(1) True semi-dynamic

Two components

(i) static

(ii) time-dependent deformation model

- examples: New Zealand NZGD2000, Canada CGVD2013, NN2000

(2) Periodically-updated

- coordinates periodically updated
- example: Israel IG05, IG05/12

Trend is for future geodetic reference frames to be semi-dynamic

The issue

The apparent drift of dynamic CRSs has been ignored

- **ETRF89 was defined to be ITRS at epoch 1989.0**
- At 2.5cm per year, by 2017 **ETRF89 differs from ITRF & ~~GNSS~~ by 75cm**
WGS 84
- **GDA94 was defined to be ITRF92 at epoch 1994.0**
- At 7cm per year, by 2017 **GDA differs from ITRF & ~~GNSS~~ by over 1.5m**
WGS 84

**With advances in real-time positioning technology
the differences can be detected**

- Australia traffic accident

Coordinate operation methods

Need to account for the temporal change of the dynamic CRS, as well as the movement of the traditional, plate-bound, CRS seen from the viewpoint of the dynamic CRS.

- **Time-dependent Helmert transformation**
 - 15 parameters
 - Two steps:
 - 1) 7 transformation parameter values for the desired epoch are computed from the rate parameters
 - 2) 7-parameter transformation applied
 - e.g. ITRFxx > ITRFyy, ITRF2008 > GDA94
- **Time-specific Helmert transformation**
 - 8 parameters
 - Two steps:
 - a) coordinates to be converted within the dynamic CRS to this time
 - b) 7-parameter transformation applied
 - e.g. PZ-90.11 to WGS 84 (G1150) [GLONASS to GPS]
- **Change of epoch** within a dynamic CRS (for time-specific step (a) above)
 - “coordinate propagation”
 - 5 parameters (3 geocentric or geographic coordinate velocities, start and finish times)
 - Velocities for station coordinates from:
 - i. Station solution
 - ii. Plate motion or deformation model

Coordinate operations

Between CRSs both with **static datum**

- No time dependency
e.g. ED50 > OSGB 1936, NGO 1948 > ED50

Between CRSs both with **dynamic datum**

- Time-dependent transformation
e.g. ITRF2008 > ITRF2014
- Time-specific transformation
e.g. PZ-90.02 > PZ-90.11

Between CRSs of different dynamism ...

- **dynamic**, **semi-dynamic**, **static**
- ... using different transformation methods
time-dependent, **time-specific**
- **with deformation or velocity grid**

Time

Time referencing has three (four) contexts:

- Dynamic **CRS** reference epoch
 - ITRF2008 reference epoch is 2005.0, ITRF2014 reference epoch is 2010.0
 - 2008 / 2014 just names
 - 2005.0 / 2010.0 = dates to which station coordinates & rates refer
- **Coordinate** data epoch
 - Attribute of data set, nothing to do with CRS definition
 - ITRF2008 @ 2014.65 \neq ITRF2008 @ 2017.23 \neq ITRF2008 [@2005.0]
- **Transformation** reference epoch, which in itself has two forms
 - a. parameter reference epoch for time-dependent transformations
 - b. transformation reference epoch for time-specific transformations
 - both of these are one of the transformation parameters

The problems

1. User confusion

- complex
- all components of the problem vary over time.

2. Inadequate metadata: coordinate epoch not clear

3. Indirect transformations

- ETRF89 > ED50 versus ETRF89 > WGS 84 > ED50

4. Time-dependent transformation methods only found in specialist software

Recommendations

1. Users need to

- be aware of whether the CRS is dynamic or static
- in addition to the CRS being identified the time [epoch] of coordinates should be recorded when using a dynamic CRS
 - ITRF2014 @ 2017.23
 - WGS 84(G1762) @ 2017.23
- convert data to common epoch before merging
- be aware that WGS 84 \approx ETRFxx (or any other ITRS-derived static CRS) is an increasingly unacceptable approximation – for sub-metre accuracies stop using it!

2. Software developers should

- add time-dependent transformation methods
- add velocity grids
- allow for coordinate epoch as a dataset attribute

What is IOGP doing?

1. Guidance Note in preparation
2. Guidance note 373-17 revision (Gulf of Mexico)
3. Additions to EPSG Dataset
 - all realizations to be added
 - ensembles to be added
 - dynamic CRSs to be identified