### Improved Operational Efficiency with Laser Scanning Scott Gray, Operations Manager, Seatronics Ltd.



an **ACTEON** company



## **Overview**

- ULS Underwater Laser Systems
- Tradeoffs with Sonar and laser
- Dynamic and Static Scanning
- Deployment Methods
- Results









### **2G Robotics**

- Founded in 2007 in Waterloo, Ontario, Canada.
- Aim to continually improve subsea imaging and measurement technology.
- Dedicated to advanced research, development, and engineering for the production of innovative and cutting-edge solutions.

### **Seatronics**

- The Marine Technology Specialists
- Global partners and distributors of 2G ULS range of systems



## **ULS Laser Systems**

seatronics





### **Trade-offs between Sonar and Laser**





## How the ULS Systems Work













### The Marine Technology Specialists

**Static** 





## **Static Deployment**





### **Vessel Deployment**





## **ROV Deployment**





## **AUV Deployment**





### **Data Processing**

- Data is captured in real-time and can be easily processed while still offshore.
- .xyz conforming to LAS data output.



Dedicated drivers in EIVA, HYPACK, and QPS software.







## **Monohansett Shipwreck**

### **Objective**

- Obtain detailed dimensional information of the archaeological site for historical records
  Solution
- ULS-500 with rotary actuator diver deployed to perform multiple stationary scans





## **Costa Concordia Parbuckling**

### **Objective**

Assess damage to underwater portion of the Costa Concordia during the salvage operation. Produce point cloud model of the entire underwater portion of starboard hull.

### Solution

ULS-500 operating in Profile mode was mounted to a pole and lowered into the water from a survey boat. The scanner produced high resolution 3D point cloud models of the damage.





## **Costa Concordia Parbuckling**









## **Structure Inspection**

### **Objective**

Stationary and dynamic scanning trials performed with ULS-500 for structure inspection

### **Solution**

Apply Capnor integrated the ULS-500 with an Oceaneering Magnum ROV, Phins 6000 INS + DVL, Gen 5 MUX and interfaced with the hydrographic survey and navigation software, QINSy.





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## **Structure Inspection**





### **Real Time QINSy Data**





## **Structure Inspection**

### **Operation**

Apply Capnor produced an accurate 3D model and designed a spool between the two flanges located on the structure using the ULS-500 data





## **Spool Metrology**

## seatronics

### Background

- 2G Robotics' ULS-500 underwater laser scanner selected by Subsea 7 for a hybrid long baseline (LBL)/laser scanning solution
- Metrology performed in the North Sea







## **Spool Metrology**

### **Objective**

Design five spool pieces to connect a newly installed bundle towhead to five previously laid spool pieces











## **Spool Metrology**

### Solution

- Entire data set captured in only 3.5 hours
- Laser scanning approach generated a complete 3D visualization comprised of 14.6 million points
- Data captured in real-time and processed while offshore





## **Pipeline Assessment**







## **Pipeline Assessment**







## **Trials with Sonardyne and MBARI**





## **Trials with Sonardyne and MBARI**





## **Trials with Sonardyne and MBARI**

- Two consecutive passes of same flange (orange & green)
- Horizontal and vertical differences 0.5 1 cm
- Orientation difference << 1 deg. Flange point clouds match plane to 1.7mm RMS!</p>
- ▶ Hub/flange orientation <<0.5 deg (likely 0.1 0.2 deg)</p>





## What does this mean for operational efficiencies?

1 hour operational ROV time per metrology is ahead
 6 baselines mapped in 1hr 45 minutes (still improving) of ROV seabed time. Speed 0.1
 m/s over structures and MAX when flying baselines

### Contactless direct hub orientation << 0.5 deg, likely 0.1-0.2 deg without "DimCon"</p>

Seabed profile Inherent part of the delivery (3D point cloud).

### Minimal Calibration

Auto-calibration, mechincal integration,... Less time, less complexity and less blunders.

## Thank you for your time. Any Questions?



